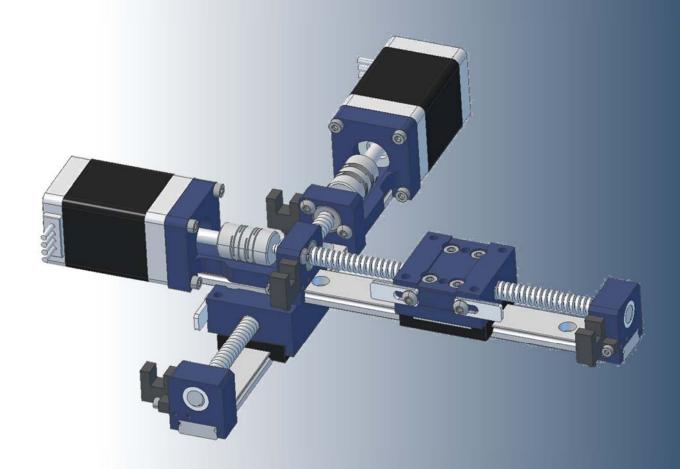


Miniature Precision Actuator Family



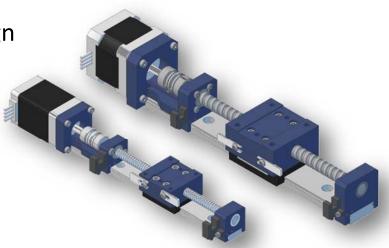
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- Simple Low Cost Design
- Compact Package
- Highly Configurable
- Maintenance Free
- Long Life



#### Introduction

The proliferation of life science and medical instruments has driven demand for lower cost, miniature motion platforms. Instrument manufacturers are forced to design their own motion platforms because existing packaged actuators are either too expensive, too heavy, or too large.

The Precision Alliance's Minibot plat form is the answer to this need. The Minibot's "minimalist" design delivers everything needed in a positioning system without the burden of unwanted costs. The Minibot is able to delivery performance and compactness at a price point you can afford to design into your machine

### **Flexibility**

The Minibot is a family of actuators built around industry standard linear guides and motor frame sizes. Each has travel selectable by the millimeter meaning you get exactly the travel needed without any extra length. Within each Minibot size there are options for various motor lengths, integrated controller/drives, various limit sensors depending on the controller type, and a variety of leadscrews and ballscrews for the speed and precision optimal for the application.

In addition to the many standard options, Minibots are easily assembled into multi-axis XY and XYZ systems or customized other ways. Customization may look like special carriage feature or the integration of payload features into the carriage, special motor windings, encoder feedback, stainless steel materials, etc.

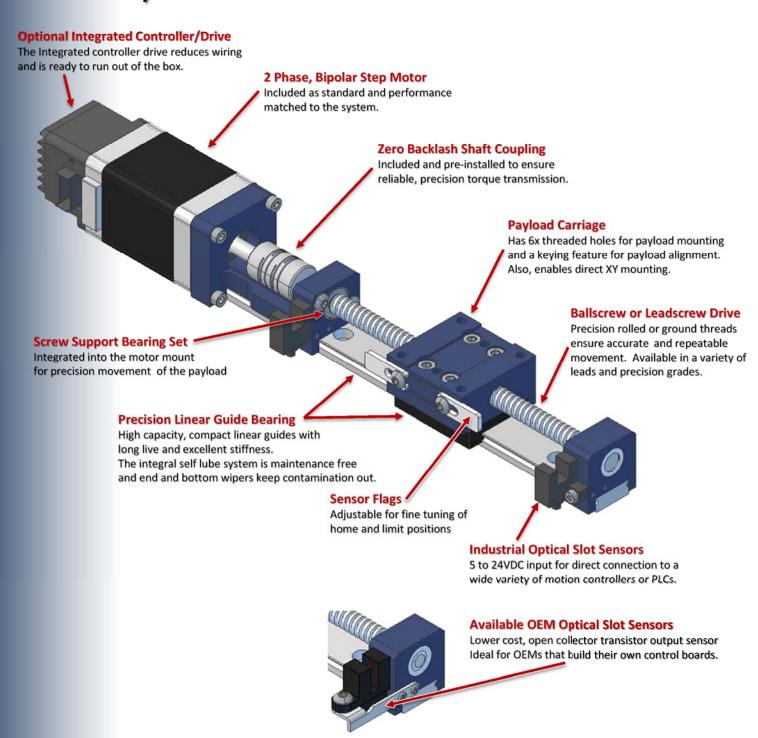
# "Everything you need in a motion platform and nothing else!"

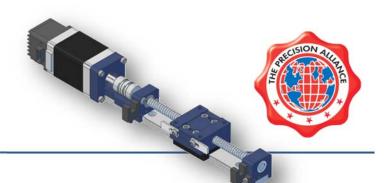


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# Anatomy of a Minibot™ Positioner

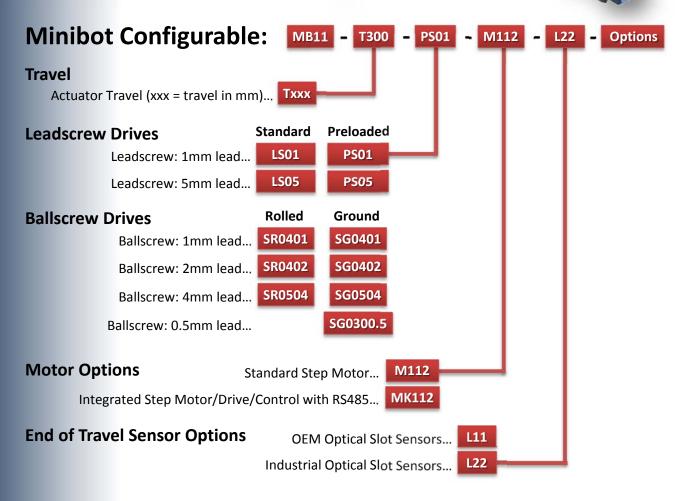




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# **MB11** Series



### **MB11** Performance Specifications

	LS01	PS01	LS05	PS05	SR0401	SG0401	SR0402	SG0402	SR0504	SG0504	SG0300.5
Screw Lead (mm/rev)	1	1	5	5	1	1	2	2	4	4	0.5
Max Travel (mm) <sup>1</sup>	300	300	300	300	300	150	300	150	300	150	300
Max Speed (mm/sec) <sup>2</sup>	15	15	75	75	15	15	30	30	60	60	7.5
Rated Thrust (N)	85	50	30	21	175	175	100	100	50	50	220
Lead Accuracy (μm/mm)	0.6	0.6	0.6	0.6	0.170	0.075	0.170	0.075	0.170	0.075	0.075
Repeatability (μm)	20	12	20	12	20	5	20	5	20	5	5
Theoretical Resolution <sup>3</sup>	0.00031	0.00031	0.00156	0.00156	0.00031	0.00031	0.00063	0.00063	0.00125	0.00125	0.00016
Straightness (μm)	Horizontal Plane: 25 μm Vertical Plane: 25 μm										
Load Capacity		Normal Load: 210 N Side Load: 210 N Roll: 1.5 Nm Yaw: 0.75 Nm Pitch: 0.75 Nm									

1) Based on 15 rps motor speed. Higher speed possible. 2) Consult factory for longer travels. 3) Based on 3200 steps/rev. Actual minimum step size will vary.

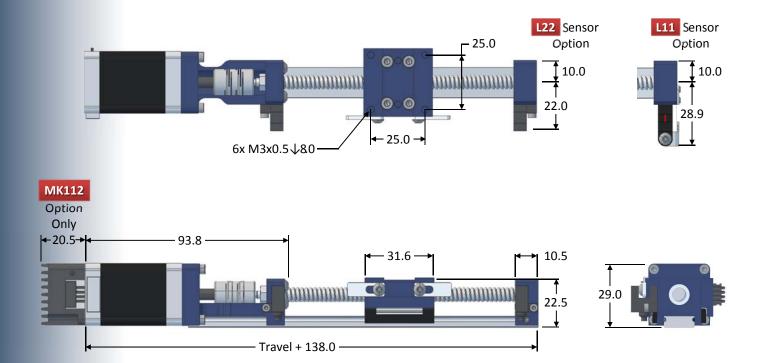


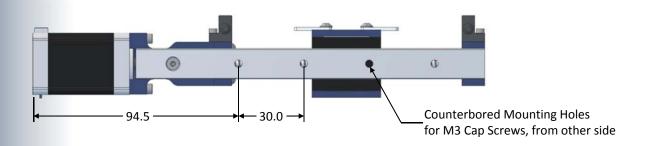


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## MB11 Dimensions (mm)





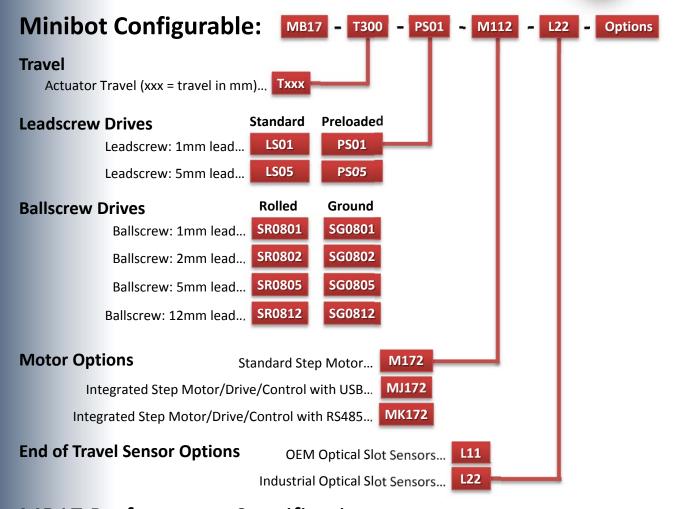
# 3D Models available at www.linearpositioningsystems.com/cad





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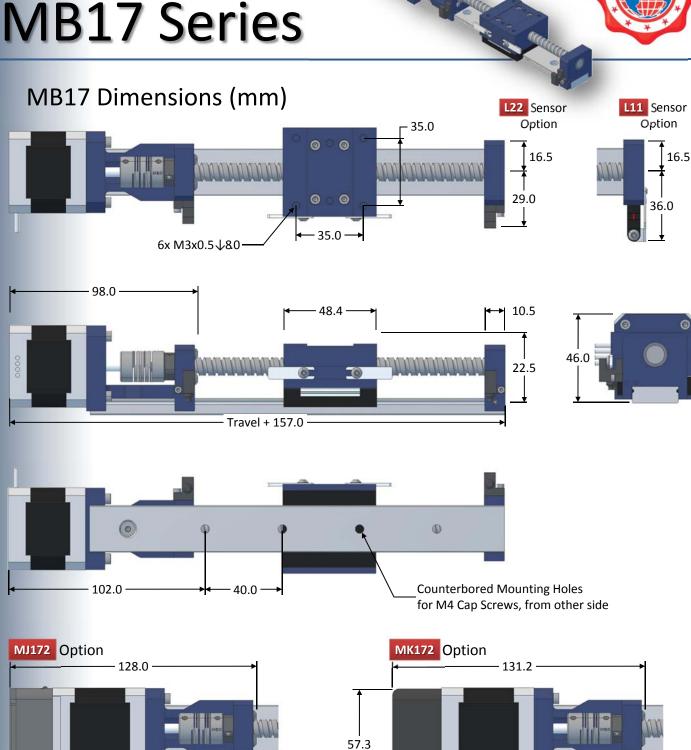
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# **MB17** Performance Specifications

	LS01	PS01	LS05	PS05	SR0801	SG0801	SR0802	SG0802	SR0805	SG0805	SR0812	SG0812
Screw Lead (mm/rev)	1	1	5	5	1	1	2	2	5	5	12	12
Max Travel (mm) <sup>1</sup>	500	500	500	500	300	150	300	150	300	150	300	150
Max Speed (mm/sec) <sup>2</sup>	10	10	50	50	10	10	20	20	50	50	120	120
Rated Thrust (N)	195	135	70	50	430	430	240	240	100	100	45	45
Lead Accuracy (µm/mm)	0.6	0.6	0.6	0.6	0.170	0.075	0.170	0.075	0.170	0.075	0.170	0.075
Repeatability (μm)	20	12	20	12	20	5	20	5	20	5	20	5
Theoretical Resolution <sup>3</sup>	0.00031	0.00031	0.00156	0.00156	0.00031	0.00031	0.00063	0.00063	0.00156	0.00156	0.00375	0.00375
Straightness (μm)	Horizontal Plane: 25 μm Vertical Plane: 25 μm											
Load Capacity		Normal Load: 520 N Side Load: 520 N Roll: 6.5 Nm Yaw: 2.5 Nm Pitch: 2.5 Nm										

1) Based on 10 rps motor speed. Higher speed possible. 2) Consult factory for longer travels. 3) Based on 3200 steps/rev. Actual minimum step size will vary.



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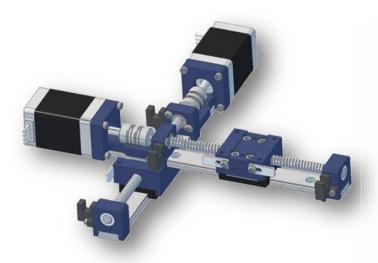


### **Multi-axis Systems**

The Minibot™ Family is designed from the start for multi-axis configurations. Both the MB11 and MB17 directly mate with another actuator of the same frame size (MB11 to MB11 or MB17 to MB17). Each carriage includes a recessed slot and threaded holes for alignment and attachment.

The XY configuration can place the Y-axis motor at 3 o'clock or 9 o'clock and center the Y-axis travel about the X-Axis or cantilever it fully to one side. A simple XY Option Code added to the part number denotes how the axes mount together.

Z-axis brackets for XZ and XYZ configurations are also available. Contact TPA for details.



#### **Payload Alignment Slot**

Controls orthogonality of the Y-Axis or payload. The slot is 1mm deep and 14mm (MB11) or 24mm (MB17) wide.

#### **Payload Mounting Holes**

Threaded holes are placed in the 4 corners of the carriage and in the alignment slot.

3D Models available at www.linearpositioningsystems.com/cad



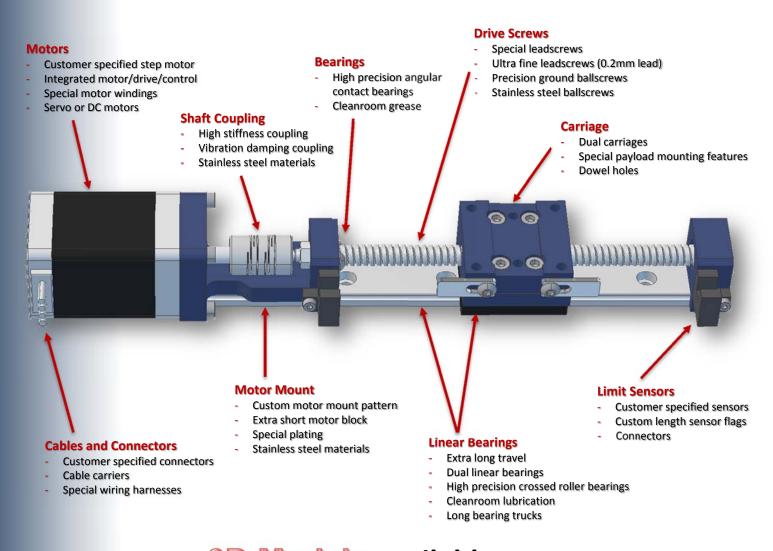
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### **Special Modifications**

Especially for OEMs, sometimes the catalog product is not exactly what is needed due to space, environmental, or other reasons; and getting it exactly the way you need it is critical for optimizing cost, and minimizing time to market. In these instances, TPA is here to help. For OEMs with special requirements, we can modify our standard Minibot™ design or even design a completely new product to precisely fit your application.

The following are some of the modifications we have or can do for you. If you do not see what you need, let us know.



# 3D Models available at www.linearpositioningsystems.com/cad

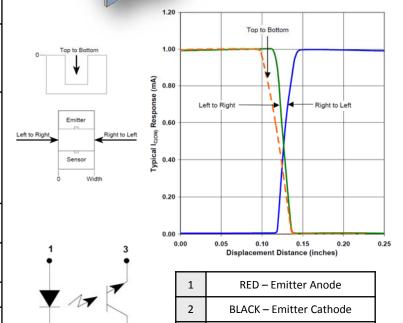


### L11

## - OEM Slot Sensor Information

Ideal for OEMs that build their own control boards

Sensor	Optek OPB880-P51Z
Input LED	Forward DC Current: 50mA Max Reverse DC Voltage: 2V Max Power Dissipation: 75mW Max $V_F$ =1.3V @ $I_F$ =20mA
Output Transistor	Collector-Emitter Voltage: 30V Max Emitter-Collector Voltage: 5V Max Collector DC Current: 30mA Max Power Dissipation: 100mW Max $V_{(BR)CEO} = 30V \text{ MIN } \textcircled{0} \text{ I}_{c} = 100 \mu\text{A} \\ V_{(BR)ECO} = 5V \text{ MIN } \textcircled{0} \text{ V}_{c} = 100 \mu\text{A} \\ I_{CEO} = 100 \text{ Max } \textcircled{0} \text{ V}_{CE} = 10V, I_F = 0, E_E = 0$
Coupled	$V_{CE(SAT)}$ =0.4V Max @ $I_{C}$ =400 $\mu$ A, $I_{F}$ =20mA $I_{C(ON)}$ =0.5mA Min @ $V_{CE}$ =10V, $I_{F}$ =20mA
Environmental	-40 to +85°C Non-condensing Humidity
Leads	26 AWG, 24" Long
Material	Polysulfone IR Transmissive Shell
Mounting Fastener	M3x6 SHCS to Bracket M2x4 Phillips Cross Recess to Body



3

4

GREEN - Transistor Emitter

WHITE - Transistor Collector

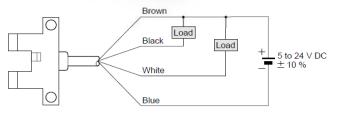
### **L22**

## - Industrial Slot Sensor Information

Ideal for wiring to motion controllers and PLCs

Power	5 to 24VDC +/-10% 15mA or less			
Output	NPN Open Collector Transistor Max Sink Current: 50mA Applied Voltage: 30VDC or less Residual Voltage (0.7V at 50mA) (0.4V at 16mA)			
Repeatability	Unidirectional: 0.03mm or better Bidirectional: 0.05mm or better Response Time: 100µs or less			
Environmental	-25 to +55°C, non-condensing humidity			
Material	PBT and Polycarbonate			
Mounting Fastener	M2x6 Socket Head Cap Screw			

#### Wiring diagram



#### **Output operation**

	Color code	Output operation		
Output 1	Black	Light-ON		
Output 2	White	Dark-ON		

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	M112	M111	M113	M172	M171	M173	
Rated Current	0.67 A <sub>RMS</sub>	0.67 A <sub>RMS</sub>	0.67 A <sub>RMS</sub>	1.68 A <sub>RMS</sub>	1.33 A <sub>RMS</sub>	1.68 A <sub>RMS</sub>	
Resistance	6.8 ohms ±10%	5.6 ohms ±10%	9.2 ohms ±10%	1.65 ohms ±10%	2.1 ohms ±10%	1.65 ohms ±10%	
Inductance	4.9 mH ±20%	4.2 mH ±20% 7.2 mH ±20%		3.2 mH ±20%	2.5 mH ±20%	2.8 mH ±20%	
Rated Voltage	4.56 V	56 V 3.8 V 6.2 V		2.8 V	2.8 V 2.8 V		
Step Angle	1.8° ± 5%, Rotation CW from front						
Temperature	Ambient: -20°C to +50°C Max Rise: 80°C						
Rotor Inertia	12E-7 Kg-m <sup>2</sup>	12E-7 Kg-m <sup>2</sup> 9E-7 Kg-m <sup>2</sup> 18E-7 Kg-m <sup>2</sup> 5.4E-8 Kg-m <sup>2</sup> 3.5E-8 Kg-m <sup>2</sup> 6.8E-8 Kg					
Weight	0.14 Kg	0.11 Kg	0.20 Kg	0.28 Kg	0.22 Kg	0.35 Kg	
Length	44.5 mm	31.5 mm	50.5 mm	40 mm	34 mm	48 mm	
Mounting Fastener	M2.5 x 12 SHCS M3 x 14 SHCS						
Wires	4x Leads, AWG26, 300mm Long; A+ (RED), A- (BLUE), B+ (BLACK), B- (GREEN)						

#### MK172, MJ172 Integrated Controller/Drive Options MK112 ,

	MK112	MK172	MJ172		
Communications	RS485	RS485/RS232	USB 2.0		
Power	12 to 24 VDC, 1.5 A max	12 to 35 VDC, 2.5 A max	12 to 24 VDC, 2.0 A max		
Inputs	Limit+, Limit-, Home 12 to 24 VDC, NPN, 0.45 mA	Limit+, Limit-, Home, 6x Digital Inputs 12 to 24 VDC, NPN, 0.45 mA	Limit+, Limit-, Home, 2x Digital Inputs 12 to 24 VDC, NPN, 0.45 mA		
Output	1x Opto-isolated PNP Output +24 VDC Max; 90 mA Max	· · · · · · · · · · · · · · · · · · ·			
Resolution	3200 Steps/rev max	3200 Steps/rev max	3200 Steps/rev max		
Max Speed	15 rps	15 rps	15 rps		
Encoder	Integrated 256 count/rev (Optional: Single Turn Absolute)	Integrated 4000 count/rev	N/A		
Operating Temp	0°C to +70°C	0°C to +70°C	0°C to +85°C		
Length	65.5 mm	65.5 mm	63 mm		
Mounting Fastener	M2.5 x 12 SHCS	M3 x 14 SHCS	M3 x 14 SHCS		

Contact TPA for additional details and product manuals

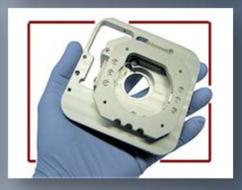
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Learn more about TPA's special systems capabilities and Instrument Motion Platforms at www.linearpositioningsystems.com



### The Precision Alliance (TPA)

4215 Pleasant Road Fort Mill, SC 29708 Phone: 800-284-9784

Fax: 803-932-1369 Email: info@tpa-us.com Web: www.tpa-us.com

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